1. Open MiniArm (“Default Program”)
    a. Inside the `setup()` unit change the code `delay(100);` to `delay(3000);`
    b. Can you now explain what these three lines of code are doing?
    ```
    tone(buzzerPin, 1000);
    delay(100);
    noTone(buzzerPin);
    ```
    c. Test by commenting out the third line:
    ```
    // noTone(buzzerPin);
    ```

2. Install “Read Data Action” library: *read_mini_actions*
    a. https://wiki.hiwonder.com/projects/miniArm/en/latest/docs/6.motion_control_basic_course.html#_6-2-1-read-action-group
    b. In `setup()` unit find the serial initialization function, `Serial.begin(9600);`
    c. In the Arduino IDE open the Serial Monitor and check that the serial transmission rate, baud, is set to 9600. Change it to another number and see what happens.
    d. At the end of the `loop()` unit add the following two lines of code:
    ```
    Serial.println("Peanut butter jelly time");
    delay(100);
    ```

3. Install “Run Action Group” library: *mini_actions_group*
    a. https://wiki.hiwonder.com/projects/miniArm/en/latest/docs/6.motion_control_basic_course.html#_6-2-2-run-action-group
    b. Check that your serial transmission rate, baud, matches the code
    c. Open the *actions.h* header file tab in the Arduino IDE
    d. Try adjusting the servo angles or adding new servo angles
    e. In the `user_task` function comment out the following line:
    ```
    // step = 1;
    ```
    f. Can you explain what’s happening?
    Note that a few lines earlier the code sets `step = 0;`